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Technical Information



R&S®NRP-Z81 Wideband Power Sensor

The sensor of choice for the analysis of radar and digital communications signals

The new R&S[®]NRP-Z81 power sensor represents latest power measurement technology. It offers all the functionality of a conventional peak power meter, and even more, in a compact unit. It can be operated on the R&S[®]NRP power meter or any Windows PC, e.g. as a cost-effective solution in production systems. No compromise was made in terms of accuracy and versatility. Therefore, this new member of the R&S[®]NRP family is particularly suitable for nearly every task in the field of power measurement:

- Analysis of radar and communications signals up to 30 MHz RF bandwidth (sensor rise time <13 ns)
- Accurate continuous average power measurements on modulated and unmodulated signals from –60 dBm to +20 dBm
- Ultrafast statistical analysis (1 million point CCDF in 25 ms)
- Frequency range from 50 MHz to 18 GHz (from 500 MHz with full video bandwidth)





R&S[®]NRP-Z81 Wideband Power Sensor

Specifications

Bold: Parameter 100 % tested.

Italics: Limits of uncertainty, calculated from the test assembly specifications and the modeled behavior of the sensor.

Normal: Compliance with specifications is ensured by the design or derived from the measurement of related parameters.

Sensor type		wideband diode power sensor			
Measurand		envelope power			
Frequency range		50 MHz to 18 GHz			
Matching (SWR)	50 MHz to 2.4 GHz	<1.16 (1.11) Even lower values can be			
values in () for temperature range 15 °C to 35 °C	>2.4 GHz to 8.0 GHz >8.0 GHz to 18.0 GHz	<1.20 (1.18) achieved by <i>Γ</i> correction <1.25 (1.23) (see top of page 6)			
RF connector		N (male)			
Power measurement range	measurement function Continuous Average Burst Average ('Full' video bandwidth) (300 kHz) Trace, Timeslot/Gate Average Statistics	1 nW to 100 mW (–60 dBm to +20 dBm 20 μW ¹ to 100 mW (–17 dBm ¹ to +20 dBm 4 μW to 100 mW (–24 dBm to +20 dBm 20 nW to 100 mW (–47 dBm to +20 dBm 3 μW ¹ to 100 mW (–25 dBm ¹ to +20 dBm			
Max. power	average power peak envelope power	0.2 W (+23 dBm) continuous 1.0 W (+30 dBm) for max. 1 μs			
Dynamic response	video bandwidth	≥30 MHz ¹⁸			
-	single-shot bandwidth	≥30 MHz ¹⁸			
	video bandwidth settings rise time 10 %/90 % $f \ge 500 \text{ MHz}$ < 500 MHz	full 5 MHz 1.5 MHz 0.3 MHz $\leq 13 \text{ ns}^{18}$ < 40 ns ¹⁸ < 75 ns < 250 ns < 1.2 µs			
	minimum burst width $(f \ge 500 \text{ MHz})$ overshoot	50 ns ≤5 %			
Acquisition	sampling rate (continuous) capture length time base accuracy time base jitter	$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			
Trigger	internal trigger range level accuracy jitter external trigger input	-30 dBm to +20 dBm (usable from -22 dBm at full video bandwidth) identical to uncertainty for absolute power measurements ≤6.3 ns see specs of R&S [®] NRP and R&S [®] NRP-Z3 USB adapter			
	trigger delay delay range delay resolution source slope (external, internal) trigger hold-off trigger dropout resolution (hold-off, dropout) trigger level threshold hysteresis	-51.2 μs to +10 s 12.5 ns bus, external, hold, immediate, internal pos./neg. 0 to 10 s 0 to 10 s 12.5 ns ±10 dB			
Zero offset ^{3,5} Typical values in ()	measurement function Continuous Average	10 μs sampling window other lengths <400 (220) pW <5 (2) nW			
	Burst/Timeslot/Gate Average Trace, Statistics	with averagingw/o averaging<10 (2) nW			

Zero drift ^{3,6}	Continuous Average	10 μs sampling windowother lengths<200 pW<500 pW		
	Burst/Timeslot/Gate Average Trace, Statistics	with averagingw/o averaging<2 nW<150 nW		
Noise ^{2,3}	measurement function Continuous Average	<200 (110) pW sampling window set		
Typical values in ()	Trace / Statistics noise per sample at video band- width	to 10 μs ⁻⁴		
	full	< 3.0 (2.0) μW		
	5 MHz	< 1.5 (1.0) µW		
	1.5 MHz	< 0.9 (0.6) µW		
	300 kHz	< 0.6 (0.4) µW		
	effect of time-gating on noise of average value	multiply "noise per sample" specification for full video bandwidth by noise reduction factors from tables B and C (page 6)		
		A minimum noise value of 5 nW or better can be achieved with adequate averaging, valid for gate lengths $\geq 2 \ \mu s$.		
	Burst/Timeslot (Gate) Average	see "effect of time-gating" above		
Uncertainty for absolute power	50 MHz to <100 MHz	0.18 dB (4.0 %)		
measurements ⁷	≥100 MHz to 700 MHz	0.14 dB (3.3 %)		
0 °C to 50 °C	>700 MHz to 4.0 GHz	0.13 dB (3.0 %)		
	>4.0 GHz to 8.0 GHz	0.15 dB (3.5 %)		
	>8.0 GHz to 18.0 GHz	0.18 dB (4.0 %)		

Additional characteristics of the R&S[®]NRP-Z81

Continuous Average function	sampling window	1 µs to 0.1 s		
Measurement of average power of station-	window shape	rectangular or von Hann ⁸		
ary signals	duty cycle correction ⁹	0.001 % to 100.00 %		
	capacity of measurement buffer	1 to 8192 results		
Burst Average function	detectable burst width	50 ns to 0.1 s		
Measurement of average burst power with	minimum gap between bursts	40 ns		
automatic detection of burst	dropout length ¹⁰ for burst end detection	0 to 0.3 s		
	exclusion periods ¹¹			
	start	0 to 0.1 s		
	end	0 to 51.2 μs		
	resolution (dropout, exclusion periods)	12.5 ns		
Timeslot (Gate) function	number of timeslots	1 to 16		
Measurement of average power in one gate	timeslot (gate) nominal width	50 ns to 0.1 s		
or in several equidistant successive time-	delay of first timeslot (gate)	see "trigger delay"		
slots	exclusion periods ¹¹			
	start	0 to 0.1 s		
	fence	0 to 0.1 s		
	end	0 to 51.2 µs		
	resolution (width, exclusion periods)	12.5 ns		
Trace function	trace length (么)	50 ns to 1 s		
Measurement of envelope power	pixels (M)	3 to 8192		
versus time	resolution (Δ/M) at video bandwidth			
	full	≥12.5 ns		
	5 MHz	≥25 ns		
	1.5 MHz	≥100 ns		
	300 kHz	≥400 ns		
	pixel representation	average, random, maximum, minimum over pixel length		
	trace start (referenced to trigger)	–4096×⊿/ <i>M</i> to 10 s		

Statistics functions	modes	CCDF and PDF histograms
Measurement of envelope power	acquisition window	
distribution	length	10 µs to 0.3 s
	delay	–51.2 μs to 10 s referenced to trigger
	exclusion periods ¹¹	
	start	0 to 0.3 s
	fence	0 to 0.3 s
	end	0 to 51.2 µs
	resolution (length, delay, ex number of classes (C)	,
	power span (S)	3 to 8192 0.01 dB to 100 dB
	class width (S/C)	≥0.006 dB
Measurement times ¹²	Continuous Average	$2 \times N \times$ (duration of sampling window
<i>N</i> : averaging factor	Continuous Average	$+ 13 \mu\text{s}) + t_z$
T: number of timeslots	buffered ¹³ , without averaging Burst Average	$2 \times \text{buffer size} \times (\text{duration of sampling} \ \text{window} + 13 \ \mu\text{s}) + t_z$
	(burst period – burst width	
	– burst dropout) > 6 μs	$\leq t_z + (N + 1) \times \text{burst period}$
	all other cases	$\leq t_z + N \times$ (burst width + burst dropout + 6 µs + burst period)
	Timeslot Average	$\leq t_{z} + (N + 1) \times$ frame length
	(frame length – <i>T</i> × nominal width) > 6 μs all other cases	
		$\leq t_z + N \times (T \times \text{nominal width} + \text{frame length} + 6 \mu\text{s})$
		<i>t_z</i> : typ. 1.6 ms
Zeroing (duration)	for all functions and frequencies	
	restricted to <500 MHz, all func	
	restricted to ≥500 MHz, all func	
	restricted to Trace and Statistic frequency range	20 ms
Averaging	modes	AUTO OFF (fixed averaging factor)
		AUTO ON (continuously auto-adapted) AUTO ONCE (automatically fixed once)
	AUTO OFF	
	supported measurement fu	nctions all
	averaging factor N Trace, Statistics	2 to 2 ¹⁶
	other	$2 \text{ to } 2^{20}$
		2.02
	AUTO ON/ONCE supported measurement fu	nctions Continuous Average, Burst Average, Time
		slot (Gate) Average
	Normal ¹⁴ operating mode	averaging factor adapted to resolution setting and power to be measured
	Fixed Noise operating mod	
	result output	
	moving	continuously, independent of averaging
	rate	factor can be limited from 0.1 s ⁻¹ to 1000 s ⁻¹
	repeat	only final result
Measurement error due to harmonics at		≤4 GHz 4 GHz to 8 GHz >8 GHz
$n \times f_0$ of carrier frequency ¹⁵	N = 2 -	-60 dBc <0.001 dB <0.002 dB <0.003 dI
		-40 dBc <0.010 dB <0.017 dB <0.025 dl
	-	-20 dBc <0.100 dB <0.170 dB <0.250 dI
	N = 3 -	-60 dBc <0.004 dB <0.003 dB <0.003 dI
		-40 dBc <0.035 dB <0.030 dB <0.025 dl
		-20 dBc <0.350 dB <0.300 dB <0.250 dI
Susceptibility of matching with respect to		change of RCO
power	–10 dBm to –60 dBm	<0.015 (0.005) values in () for tem-
	-10 dBm to 0 dBm	<pre><0.035 (0.025) perature range 15 °C to 35 °C and frequen-</pre>
	-10 dBm to +10 dBm	(0.073 (0.050)) cies < 4 GHz
	–10 dBm to +20 dBm	<0.090 (0.060)

4(8)

Г correction	function	reducing the influence of mismatched sources		
	parameters	magnitude and phase of reflection coeffi- cient of source		
	residual SWR	<1.06 in temperature range 15 °C to 35 °C		
Attenuation correction	function	correcting the measurement result by means of a fixed factor (dB offset)		
	range	-100.000 dB to +100.000 dB		
S-parameter correction	function	taking into account a component connected to the sensor input by loading its s-parameter data set into the sensor		
	parameters	$s_{11}, s_{21}, s_{12}, s_{22}$ (in s2p format)		
	number of independently addressable data sets	freely definable		
	total number of frequencies (sum of all data sets)	32000		
Calibration uncertainty ¹⁶	50 MHz to <100 MHz	0.120 dB (2.8 %)		
	≥ 100 MHz to 700 MHz	0.075 dB (1.8 %)		
20 °C to 25 °C	> 700 MHz to 2.0 GHz	0.065 dB (1.5 %)		
	> 2.0 GHz to 4.0 GHz	0.070 dB (1.6 %)		
	> 4.0 GHz to 8.0 GHz	0.085 dB (2.0 %)		
	> 8.0 GHz to 12.5 GHz	0.090 dB (2.1 %)		
	>12.5 GHz to 18.0 GHz	0.120 dB (2.8 %)		

General data

Interface to host	power supply	+5 V / typ. 500 mA (USB high-power de- vice)
	remote control	as a USB device (function) in full-speed mode, compatible with USB 1.0/1.1/2.0 specifications
	trigger input	differential (0 V/+3.3 V)
Dimensions	W×H×L	48 mm × 31 mm × 170 mm
	length incl. connecting cable	approx. 1.6 m
Weight		<0.3 kg
Temperature loading		
Operating range and permissible range ¹⁷	permissible range in []	0 °C [–10 °C] to +50 °C [+55 °C] in line with IEC 60068
Storage range		–40 °C to +70 °C
Climatic resistance		in line with IEC 60068
Damp heat		+25 °C/+40 °C cyclic at 95 % relative hu- midity without condensation
Mechanical resistance		
Vibration, sinusoidal		in line with IEC 60068 5 Hz to 55 Hz, max. 2 g 55 Hz to 150 Hz, 0.5 g constant
Vibration, random		in line with IEC 60068 10 Hz to 500 Hz, 1.9 g (rms)
Shock		in line with IEC 60068; 40 g shock spec- trum
Air pressure	operation	795 hPa (2000 m) to 1060 hPa
	transport	566 hPa (4500 m) to 1060 hPa
Electromagnetic compatibility		in line with EN 61326, EN 55011
Safety		in line with EN 61010-1
Calibration interval		2 years

Table A Multipliers for noise, zero offset, and zero drift specifications

Use these multipliers for the calculation of noise, zero offset, and zero drift when operating the sensor outside the square law region, at frequencies below 500 MHz, or at temperatures different from 23°C.

	≤–20 dBm	–10 dBm	–5 dBm	0 dBm	5 dBm	10 dBm	15 dBm	20 dBm
0 °C	0.8 [0.9]	0.9 [1.0]	1.4 [1.5]	3.2 [3.5]	7.5 [8.5]			
15 °C	0.9 [1.0]	1.1 [1.2]	1.6 [1.8]	3.4 [3.6]	7.5 [8.5]			
23 °C	1.0 [1.2]	1.3 [1.5]	1.8 [2.0]	3.5 [3.8]	7.6 [8.7]	17 [18]	35 [37]	65 [70]
35 °C	1.4 [1.7]	1.7 [2.1]	2.3 [2.6]	3.9 [4.3]	7.8 [9.0]			
50 °C	2.5 [3.0]	2.7 [3.3]	3.3 [4.0]	5.2 [5.4]	8.7 [9.5]			

[] at frequencies <500 MHz

Table B Noise reduction factors for gating and smoothing

The noise reduction factors in this table describe how noise is reduced if adjacent samples are averaged for the measurement of mean power over a time interval. The time interval can be the length of a gate, timeslot, or pixel in trace mode. Without averaging or for single events, use the leftmost column. With averaging activated, use the columns for the individual repetition rates, and additionally apply reduction factors from table B. The repetition rate is identical to the frequency of the measurement being carried out, i.e. the inverse of the trigger period.

Repetition rate → Gate (point) width	0	10 s ^{−1}	100 s ⁻¹	10 ³ s ⁻¹	10 ⁴ s ⁻¹	5×10 ⁴ s ⁻¹	10 ⁵ s ⁻¹			
25 ns			I	0.7						
50 ns				0.5						
100 ns		0.4								
200 ns	0.3									
500 ns		0.2								
1 µs	0.16	0.	15		(.14				
2 µs	0.14	0.13	0.12	0.11		0.10				
10 µs	0.11	0.1	0.09	0.08	0.07	0.06				
100 µs	0.10	0.09	0.07	0.06	0.04					
1 ms	0.10	0.07	0.06	0.035						
10 ms	0.10	0.06	0.035							

 Table C
 Noise reduction factors for averaging (see footnote ⁴ for Continuous Average function)

Averaging no.	2	4	8	16	32	64	128	256	512	1 k	2 k	4 k	8 k
Reduction factor	0.7	0.5	0.35	0.25	0.18	0.13	0.09	0.063	0.044	0.031	0.022	0.016	0.011

Example: A power measurement on a radar pulse is carried out by means of the Timeslot (Gate) function. Nominal width is set to 1 μ s, and the averaging factor to 32. The pulse repetition rate is 100 Hz, and the measurement is performed at 15°C ambient temperature. The measured value is about –10 dBm.

Sample noise (2 σ) under reference conditions is max. 3 μ W. Applying the multiplier of 1.1 specified in table A results in 3.3 μ W sample noise under measurement conditions. Gating results in a noise reduction factor of 0.15 (table B), and averaging in a reduction factor of 0.18 (table C). Residual noise can then be calculated as follows: 3.3 μ W × 0.15 × 0.18 = 89 nW (approximately 0.1% of measured value).

¹ With full video bandwidth. Reduce specified minimum levels in accordance with the reduction of sampling noise at lower bandwidths.

- ² Measured over a one-minute interval, at constant temperature, two standard deviations.
- ³ Specifications are valid at 23 °C ambient temperature for power levels <-20 dBm and frequencies ≥500 MHz. For measurements at other temperatures, frequencies and/or levels, use the multipliers from table A.
- ⁴ 512 k averages taken with the sampling window set to 10 μs (default). Noise with other averaging numbers can be calculated using the multipliers indicated below:

Averaging number	512 k	128 k	32 k	8 k	2 k	512	128	32	8
Integration time	10.5 s	3.9 s	1.0 s	0.25 s	60 ms	15 ms	3.8 ms	1.0 ms	0.24 ms
Noise multiplier	1	2	4	8	16	32	64	128	256

A sampling window length of 10 μ s is optimal with respect to noise for a specific total integration time. Increasing the length above 10 μ s, e.g. for effectively suppressing modulation-induced fluctuations of the measurement result, only lowers the noise contribution of the sampling window itself, i.e. 50 % maximum for lengths >100 μ s. Since the number of sampling windows is inversely proportional to their length for a specific integration time, total noise increases with lengths other than 10 μ s.

- ⁵ Specification in terms of an expanded uncertainty with a confidence level of 95 % (two standard deviations). For calculating zero offsets at higher confidence levels, use the properties of the normal distribution (e.g. 99.7 % confidence level for three standard deviations).
- ⁶ Within 1 hour after zeroing, permissible temperature change ±1 °C, following a 2-hour warm-up of power sensor.
- ⁷ Expanded uncertainty (k=2) for absolute power measurements on CW signals.
- ⁸ Preferably used with determined modulation when the duration of the measurement window cannot be matched to the modulation period. Compared to a rectangular window, noise is about 22 % higher.
- ⁹ For calculating the pulse power of periodic bursts from an average power measurement.
- ¹⁰ This parameter enables power measurements on modulated bursts. The parameter must be longer in duration than modulationinduced power drops within the burst.
- ¹¹ To exclude unwanted portions at the beginning, at the end or in the measurement window from the measurement result.
- ¹² Valid for Repeat mode, extending from the beginning to the end of all transfers via the USB interface of the power sensor. Measurement times in the case of remote control of the R&S®NRP base unit via the IEC625/IEEE488 bus are approximately 2.5 ms longer, extending from the start of the measurement to the moment when the measurement result is supplied to the output buffer of the R&S®NRP.
- ¹³ To increase measurement speed, the power sensor can be operated in buffered mode. In this mode, measurement results are stored in a buffer of user-definable size and then output as a block of data when the buffer is full. To enhance measurement speed even further, the sensor can be set to record the entire series of measurements when triggered by a single event. In this case, the power sensor automatically starts a new measurement as soon as it completes the preceding one.
- ¹⁴ Characteristics like a conventional power meter. The averaging factor increases continuously as power decreases, but not to the extent that would be necessary to keep the relative noise content at the same level.
- ¹⁵ Magnitude of measurement error referenced to an ideal thermal power sensor that measures the sum power of carrier and harmonics. For power levels below –10 dBm, the specifications for 2×*f*₀ (3×*f*₀) can be lowered by a factor of √10 (10) per 10 dB below –10 dBm. Example: At 12 GHz / –30 dBm, the influence of the second harmonic, suppressed by 30 dBc, will cause an error of max. 0.025 dB × √10 ÷ 10 = 0.008 dB. Standard uncertainties can be assumed to be half the values.
- ¹⁶ Expanded uncertainty (k=2) for absolute power measurements on CW signals at a calibration level of –10 dBm and at calibration frequencies (50/55/60/68/80/100/200/300/400/499.99/500/600/720/850 MHz; from 1 GHz to 18 GHz in steps of 0.5 GHz).
- ¹⁷ The operating temperature range defines the span of ambient temperature in which the instrument complies with specifications. In the permissible temperature range, the instrument functions but adherence to specifications is not warranted.
- ¹⁸ Specifications are valid from 15°C to 50°C ambient temperature. Below 15°C, video bandwidth and single shot bandwidth continuously decrease down to 20 MHz typically at 0°C. Accordingly, sensor rise time increases up to 50 ns for signals below 500 MHz and up to 20 ns for all other frequencies (at 0°C).

Accessories

See the R&S[®]NRP data sheet (PD 0757.7023.21)

Ordering information

Designation	Туре	Order No.
Wideband Power Sensor	R&S [®] NRP-Z81	1137.9009.02
1 nW to 100 mW; 50 MHz to 18 GHz		



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